

Figure 1

FIG. 2 is a schematic diagram of a system 100, according to one embodiment of the present invention. The system 100 includes a first component 110, a second component 120, a third component 130, a fourth component 140, a fifth component 150, a sixth component 160, a seventh component 170, an eighth component 180, a ninth component 190, a tenth component 200, an eleventh component 210, a twelfth component 220, a thirteenth component 230, and a fourteenth component 240. The first component 110 is connected to the second component 120, which is connected to the third component 130. The third component 130 is connected to the fourth component 140, which is connected to the fifth component 150. The fifth component 150 is connected to the sixth component 160, which is connected to the seventh component 170. The seventh component 170 is connected to the eighth component 180, which is connected to the ninth component 190. The ninth component 190 is connected to the tenth component 200, which is connected to the eleventh component 210. The eleventh component 210 is connected to the twelfth component 220, which is connected to the thirteenth component 230. The thirteenth component 230 is connected to the fourteenth component 240.

2/7

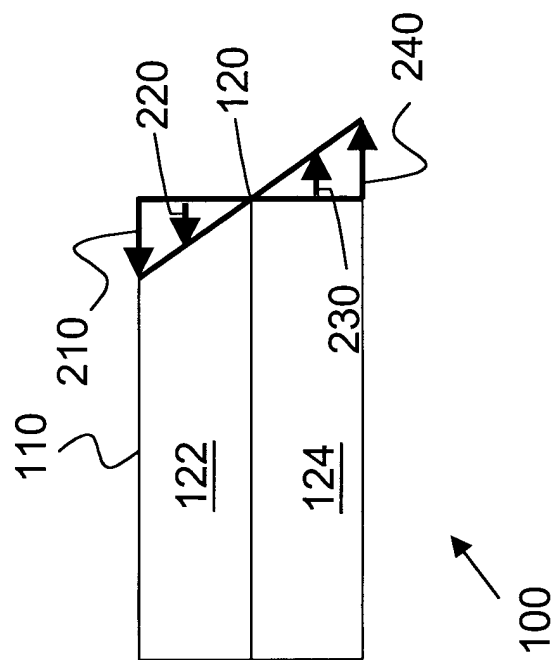


Figure 2

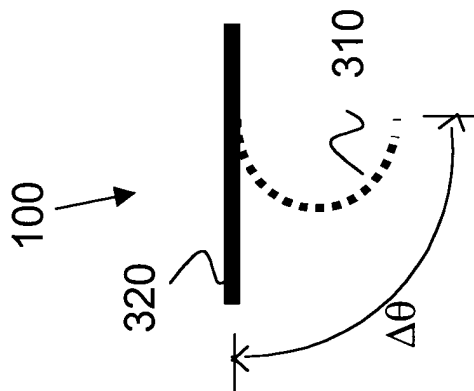


Figure 3

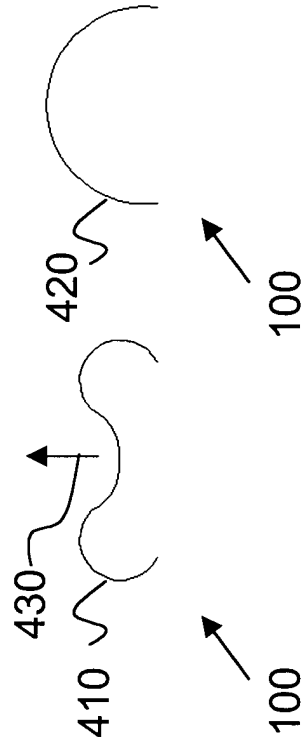


Figure 4

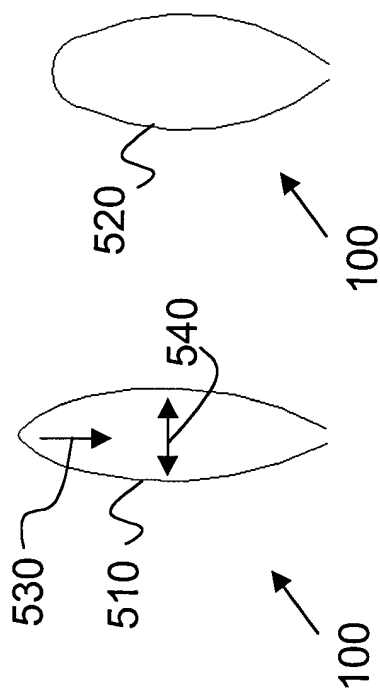


Figure 5

FIG. 6 is a schematic diagram of a system 600 for measuring a change in angle  $\Delta\theta$  of a beam 620. The system 600 includes a beam 620, a detector 610, a light source 630, a lens 640, and a mirror 650. The beam 620 is directed towards the detector 610. The light source 630 is directed towards the lens 640. The lens 640 is directed towards the mirror 650. The mirror 650 is directed towards the beam 620. The change in angle  $\Delta\theta$  is indicated by a curved arrow between the beam 620 and the detector 610.

6/7

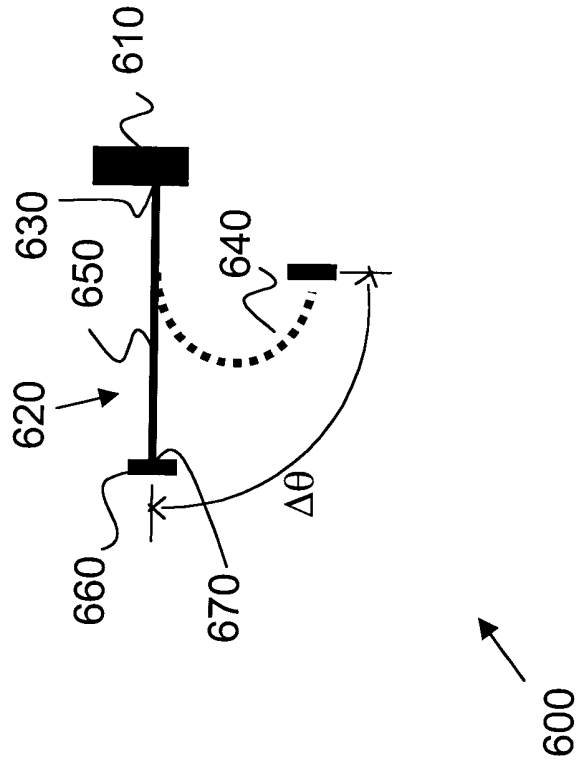


Figure 6

7/7

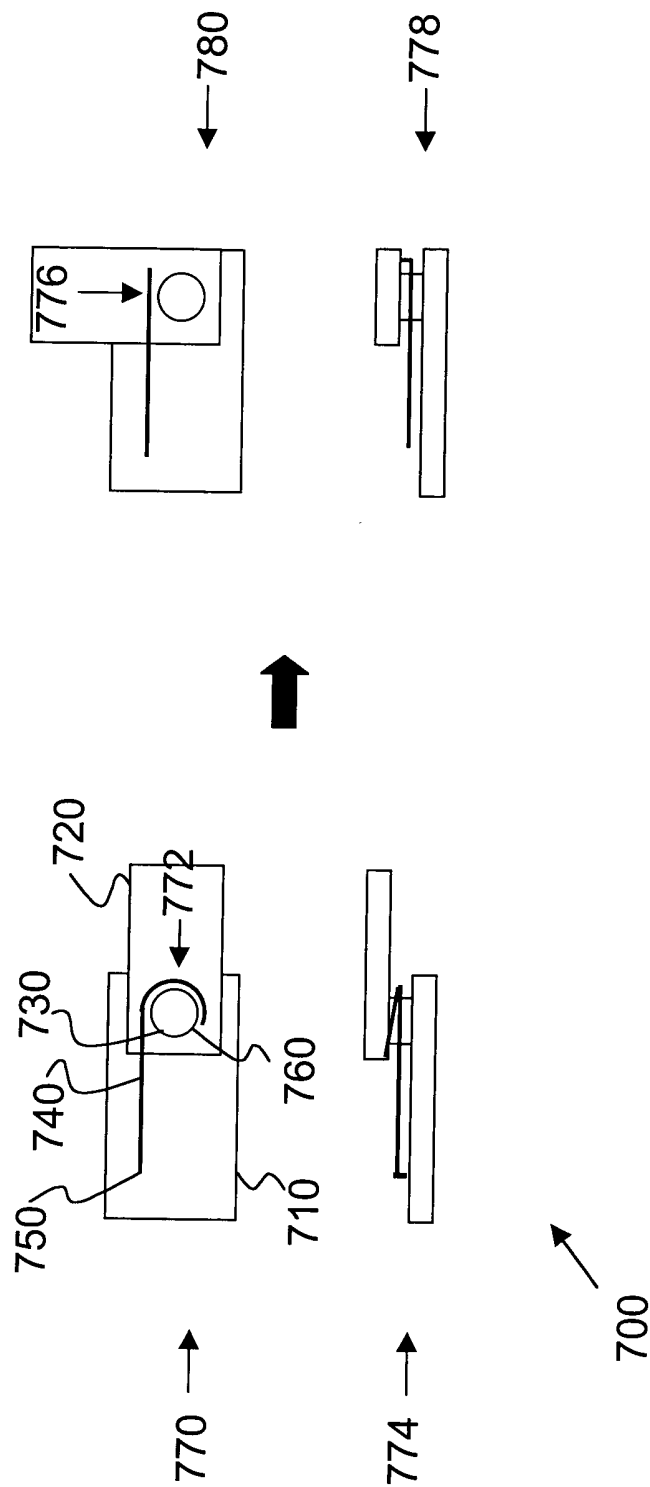


Figure 7